

Other Attacks & Applications

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Agenda



- Privacy Attack
- Physical Attack
- Non-Security Application
- Conclusion

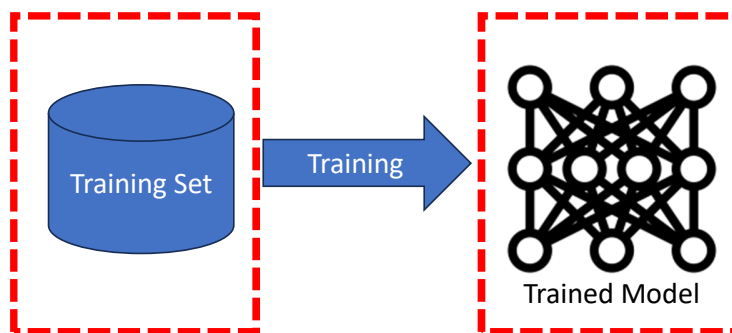
Privacy Attack



Objective



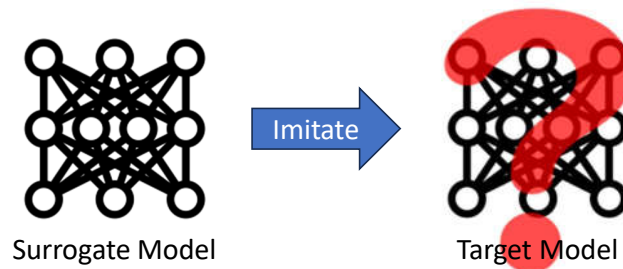
- Model Stealing
- Training Set Recovery



Model Stealing



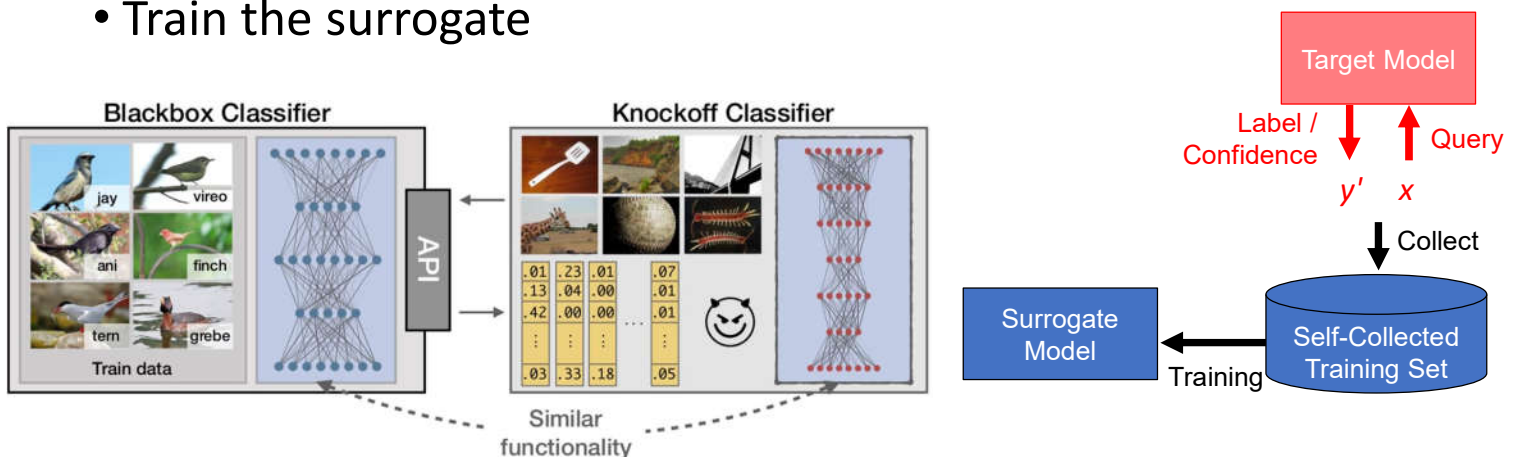
- Construct a copy of a model
- Two possible goals:
 - Intellectual property for well performance
 - Surrogate model for evasion attack



Model Stealing Query Attack

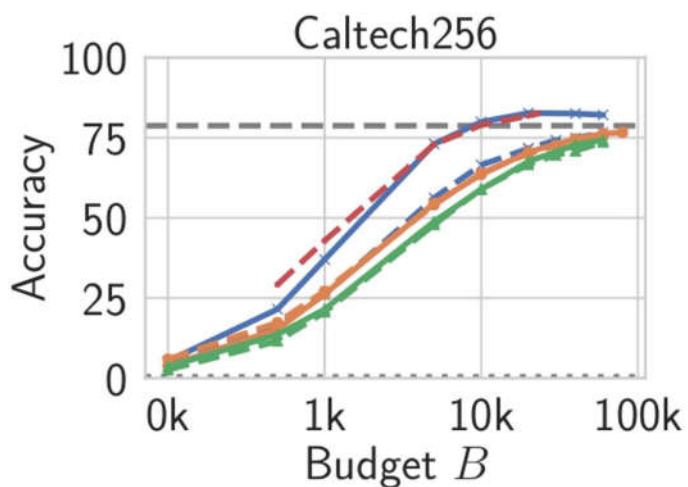


- Procedure
 - Query the target model and collect output
 - Train the surrogate





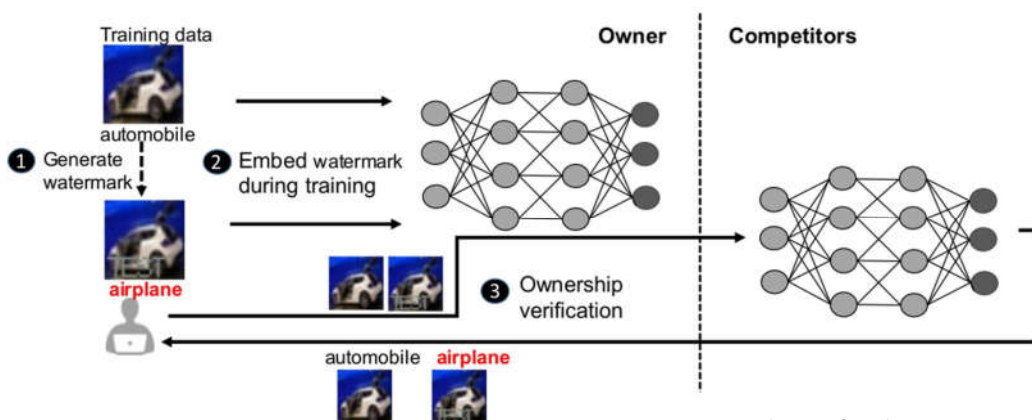
- How to generate query samples?
 - Select samples randomly
 - May not be effective
 - Many queries are required
 - Select/Generate samples specifically according to
 - High Output Confidence: Only the confident samples
 - High Diversity: Different information



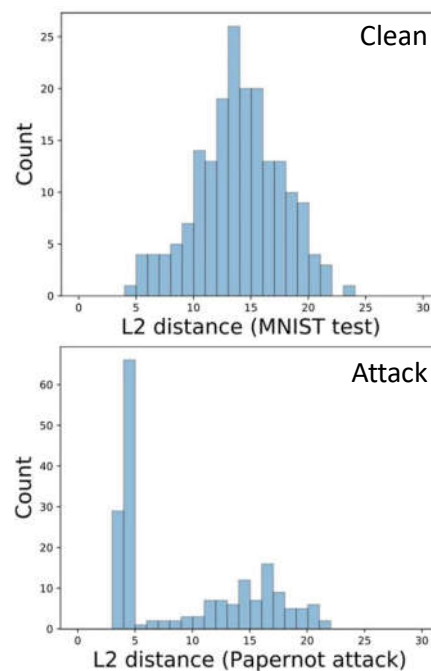
- ILSVRC overlap 42%
- D^2 dataset made by ILSVRC, OpenImg, and others.
- P_V same dataset used to train the Target
- OpenImg overlap 44%
- adaptive High confidence + High Diversity
- random Random set



- Add **watermarks** to the model for the **proof of intellectual property**
 - Watermarks: **patterns** that cause an **unexpected misclassification** when added to an image



- Understand that attackers are querying the model and block them.
- Distance between consecutive queries for a legitimate purpose usually follow a normal distribution, but not for an attack

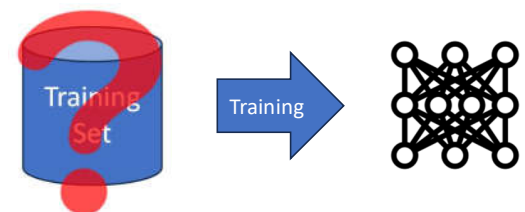
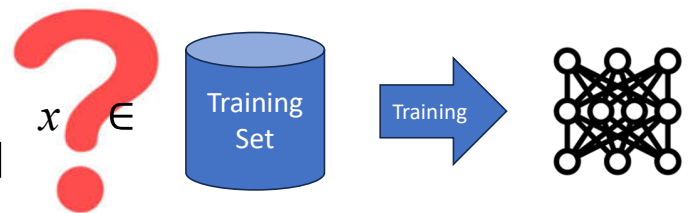




- Training samples may contain sensitive information
 - Personal information
 - Financial information
 - Images of suspected people
- Even if recovered training samples are incomplete, they can still be combined to re-identify individuals.



- Different Levels of Recovery
 - Training Sample Identification
 - Identify whether a sample used in training
 - Training Sample Reconstruction
 - Construct the training set according to the model

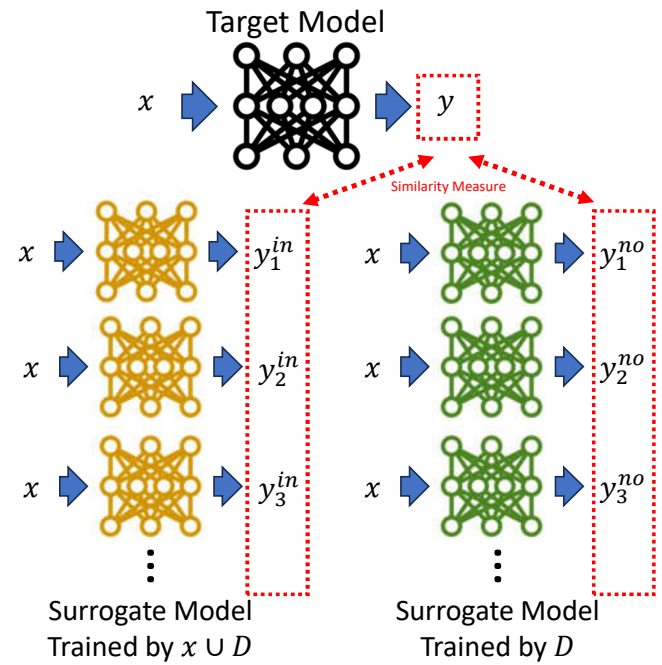


Training Set Recovery

Training Sample Identification

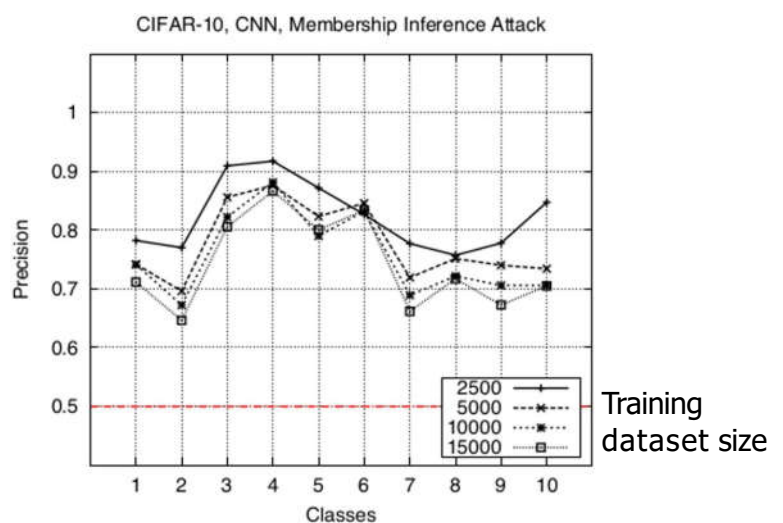
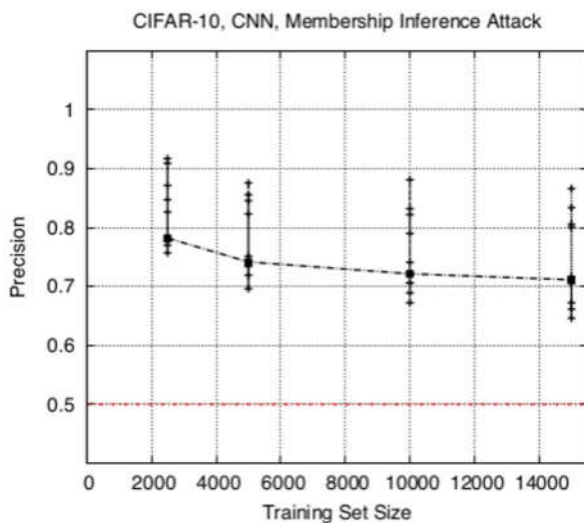


- Membership Inference Attacks
 - Query the target model with the input sample x
 - Many surrogate model pairs are crafted:
 - including x in the training dataset
 - not including x in the training dataset
 - Determine whether the sample is used in training by comparing the predictions of those surrogate models with the target model



Training Set Recovery

Training Sample Identification





• Model Inversion Attack

- Reconstruct a training sample by maximizing confidence with respect to the target label using gradient descent
- Query ability is required

Algorithm 1 Inversion attack for facial recognition models.

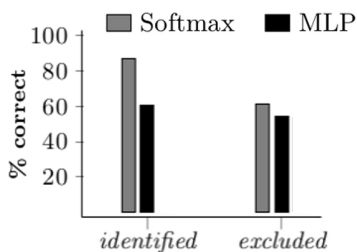
```

1: function MI-FACE(label, α, β, γ, λ)
2:   c(x)  $\stackrel{\text{def}}{=} 1 - \hat{f}_{\text{label}}(\mathbf{x}) + \text{AUXTERM}(\mathbf{x})$ 
3:   x0 ← 0
4:   for i ← 1 ... α do
5:     xi ← PROCESS(xi-1 - λ · ∇c(xi-1))
6:     if c(xi) ≥ max(c(xi-1), ..., c(xi-β)) then
7:       break
8:     if c(xi) ≤ γ then
9:       break
10:  return [arg minxi(c(xi)), minxi(c(xi))]
    
```

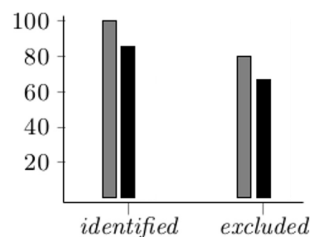


- Mechanical Turk workers are asked to match the reconstructed image to one of five face images from the original training set

	Identify by Workers	Cannot Identify by Workers
Present in the selected images	Identified	Not Match
Not present in the selected images	Not Match	Excluded



(a) Average over all responses.



(c) Accuracy with skilled workers.



Target

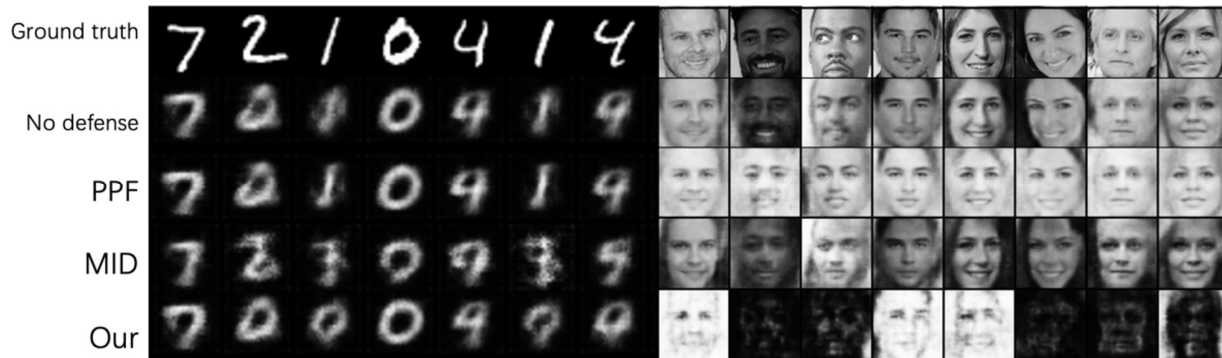
Softmax

MLP

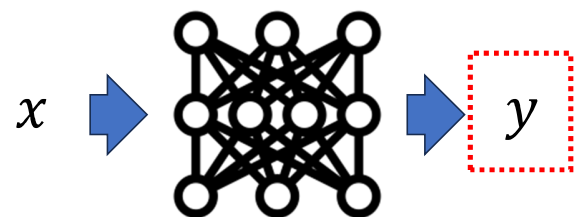


- Maximize the reconstruction error without changing the labels

$$\begin{aligned} & \max \mathcal{R}(x, \mathcal{A}(y + e)) && \text{reconstruction error} \\ \text{subject to: } & e \leq \epsilon && \text{upper bound on modification} \\ & \arg \max(y + e) = \arg \max y && \text{same predicted labels on original and attack samples} \\ & 0 \leq (y_i + e_i) \leq 1, \sum (y_i + e_i) = 1 && \text{Probability maintenance} \end{aligned}$$

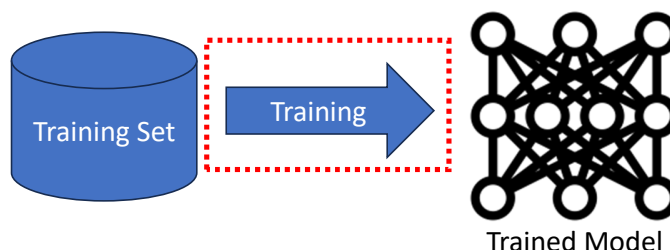


- Privacy attacks usually assume knowledge of the classifier's scores
- Control the outputs of queries:
 - Score Blocking: provide only label but not scores for classes
 - Scores Perturbation: reduce reliability of scores





- Deep neural networks tend to memorize training data (they are really confident when predicting them)
- Considering additional terms that are irrelevant to the samples, such as regularization, can reduce memorization on the training samples



[1] Feldman et al., What Neural Networks Memorize and Why..., NeurIPS 2020

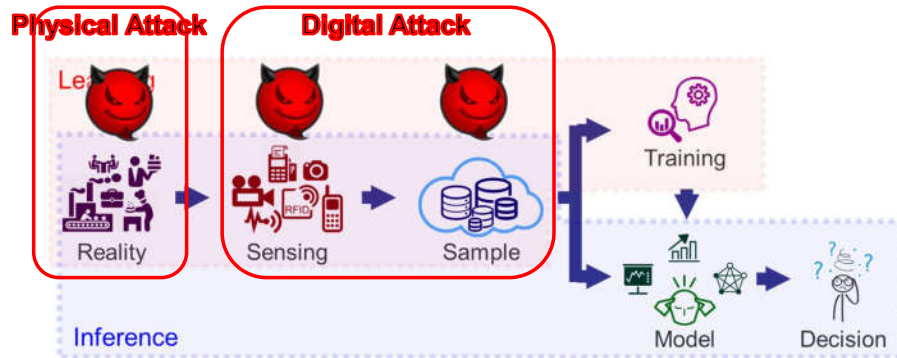
Physical Attack



Physical Attack



- Previous discussion focuses on **digital representation**
- Input can be **precisely controlled**
- Can adversarial attack be applied to our real world?



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Mahmood Sharif, Sruti Bhagavatula, Lujjo Bauer(2016) Accessorize to a crime: Real and stealthy attacks on state-of-the-art face recognition. In: 2016 acm sigsac conference on computer and communications security

Physical Attack



- A printed contaminated stop sign



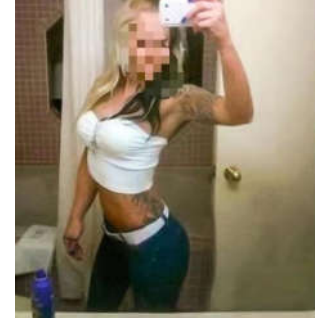
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Physical VS Digital World



- **Gap** between physical and digital world
 - **Spatial Constraints**
 - **Adversarial noise** should only appears on the **object** but **not** the **background**
 - **Physical Limits on Imperceptibility**
 - **Small perturbations** are almost **imperceptible** to sensors
 - **Environmental Conditions**
 - **Distance, angle, lighting/weather conditions**
 - **Fabrication Error**
 - **Reproduction error**, e.g. printer limitation



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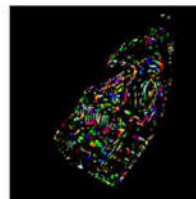
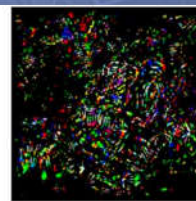
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Kevin Eykholt, Ivan Evtimov, Earlene Fernandes (2017) Robust Physical-World Attacks on Deep Learning Visual Classification. In: Proceedings of the IEEE conference on computer vision and pattern recognition

Attack Region



- **Digital Attack**
 - Any features
 - Cannot be used in reality
- **Poster/Wrapper Attack**
 - Features in object
- **Sticker Attack**
 - Features is a small area
 - Easier to implement



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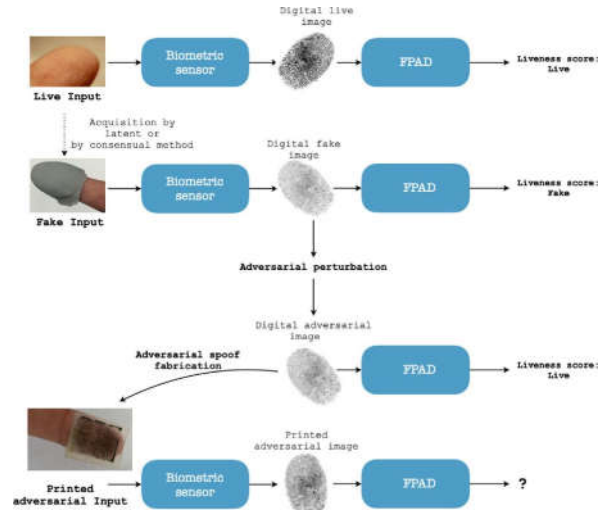
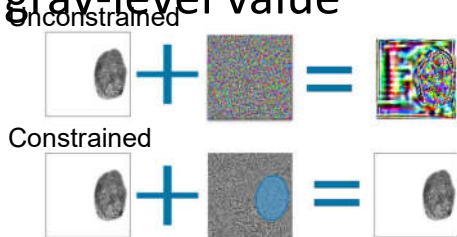
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M Melis, A Demontis, B Biggio(2017) Is Deep Learning Safe for Robot Vision? Adversarial Examples against the iCub Humanoid. In: Proceedings of the IEEE International Conference on Computer Vision Workshops



- Evade fingerprint liveness detection
- Attack is limited:

- **Region:**
Actual fingerprint
- **Value:**
only gray-level value



S Marrone, R Casula, G Orrù(2020) Fingerprint Adversarial Presentation Attack in the Physical Domain. In: ICPR



- Only attack the features in a glass mask



Attack the whole face



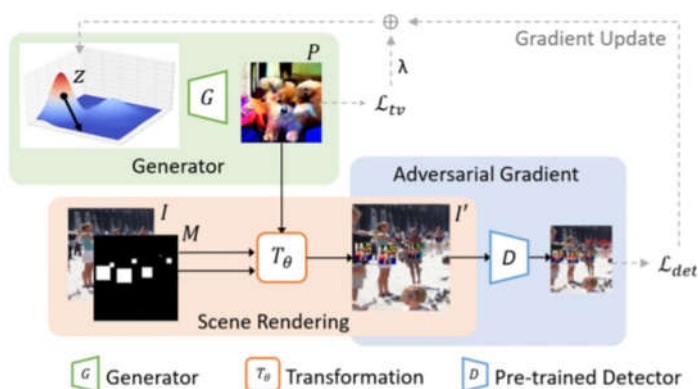
Attack the glass region



M Sharif, S Bhagavatula, L Bauer (2016) Accessorize to a Crime: Real and Stealthy Attacks on State-of-the-Art Face Recognition. In: Proceedings of the 2016 ACM SIGSAC conference on computer and communications security



- Embed a generated image to a clothing region



$$L_{det} = \frac{1}{N} \sum_{i=1}^N \max_j [D_{obj}^j(I'_i) D_{cls}^j(I'_i)]$$

adversarial detection loss

$$L_{tv} = \sum_{i,j} \sqrt{(P_{i+1,j} - P_{i,j})^2 + (P_{i,j+1} - P_{i,j})^2}$$

smoothness of a generated image

YCT Hu, BH Kung, DS Tan(2023) Naturalistic Physical Adversarial Patch for Object Detectors. In: ICCV

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Limit Attack Region is not enough



- Objects can be viewed from different distances and angles
- **Distance**: Approach to a printed contaminated stop sign
 - **Misclassified** as “sports ball” in **two frames**
- **Angle**: Camera moves closely around a printed original and contaminated stop signs
 - **Misclassified** as “toilet” in **two frames**

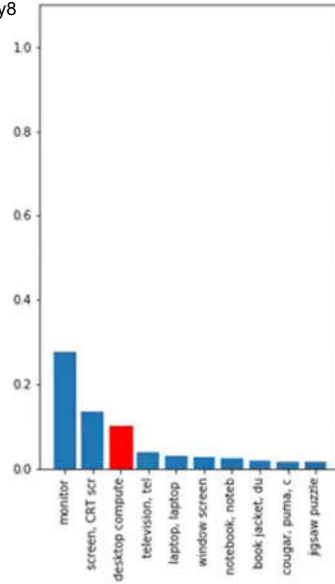


Environmental Conditions

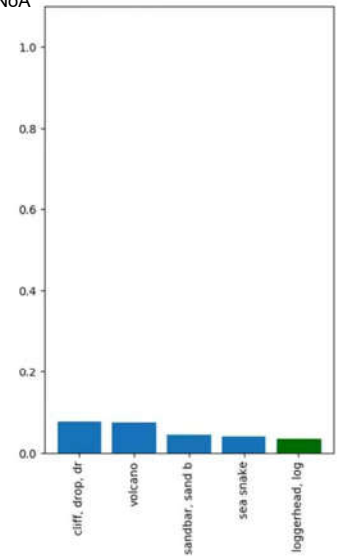


• Expectation Over Transformation (EOT)

<https://www.youtube.com/watch?v=oeQW5qdey8>



<https://www.youtube.com/watch?v=YXy6oX1iNoA>



Anish Athalye, Logan Engstrom, Andrew Ilyas(2018) Synthesizing Robust Adversarial Examples. In: International conference on machine learning

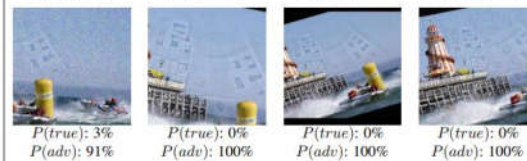
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Environmental Conditions

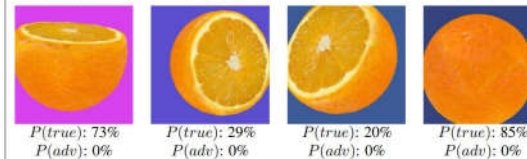


2D Image

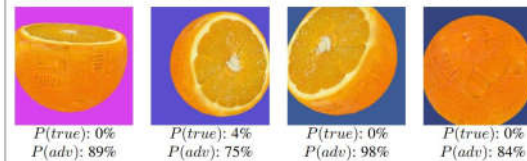


3D Model

Original: orange



Adv: power drill

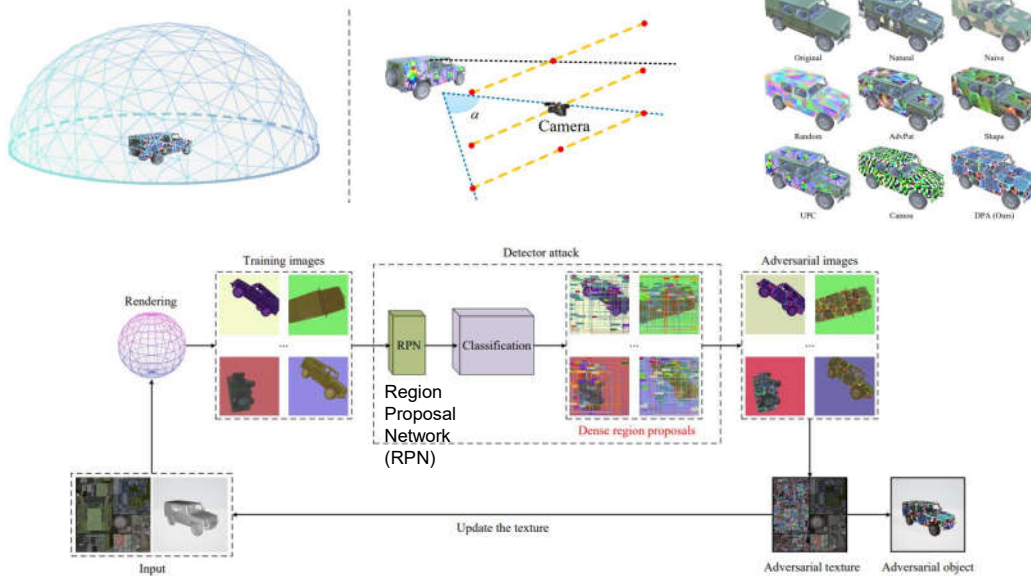


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- Consider **different angles** in reality



Yexin Duan, Jialin Chen, Xingyu Zhou(2023) DPA: Learning Robust Physical Adversarial Camouflages for Object Detectors. In:arXiv

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Imperceptibility & Fabrication Error



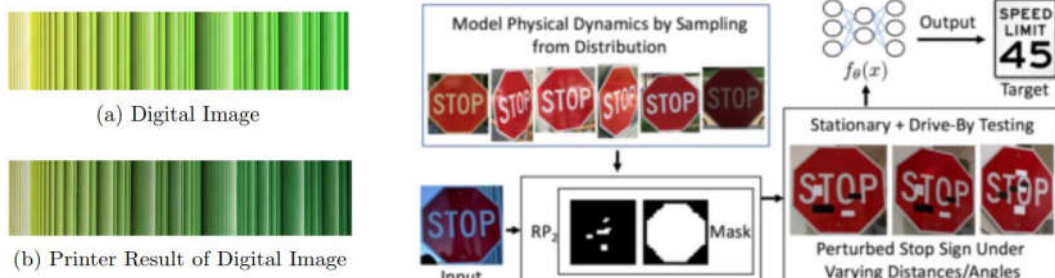
- Consider printability
- **Robust Physical Perturbations (RPP)**

$$\operatorname{argmin}_{\delta} \lambda \|M_x \cdot \delta\|_p + \text{NPS}(M_x \cdot \delta) + \mathbb{E}_{x_i \sim X^v} J(f_{\theta}(x_i + T_i(M_x \cdot \delta)), y^*)$$

Manipulation Restriction
Non-Printability Score (NPS)
Attack performance after different transformations

where

M_x : Mask δ : Perturbation
 X_v : set of victim images (under different transformations)



Imperceptibility & Fabrication Error



Distance/Angle	Subtle Poster	Subtle Poster Right Turn	Camouflage Graffiti	Camouflage Art (LISA-CNN)	Camouflage Art (GTSRB-CNN)
5' 0°					
5' 15°					
10' 0°					
10' 30°					
40' 0°					
Targeted-Attack Success	100%	73.33%	66.67%	100%	80%

Poster Attack



(a) The poster attack inside



(b) The poster attack outside

Sticker Attack



(c) The sticker attack inside



(d) The sticker attack outside

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Kevin Eykholt, Ivan Evtimov, Earlene Fernandes (2017) Robust Physical-World Attacks on Deep Learning Visual Classification. In: Proceedings of the IEEE conference on computer vision and pattern recognition

Natural Modification



- Samples are crafted more naturally



Attack modification is obvious



Attack modification is natural
More concealment

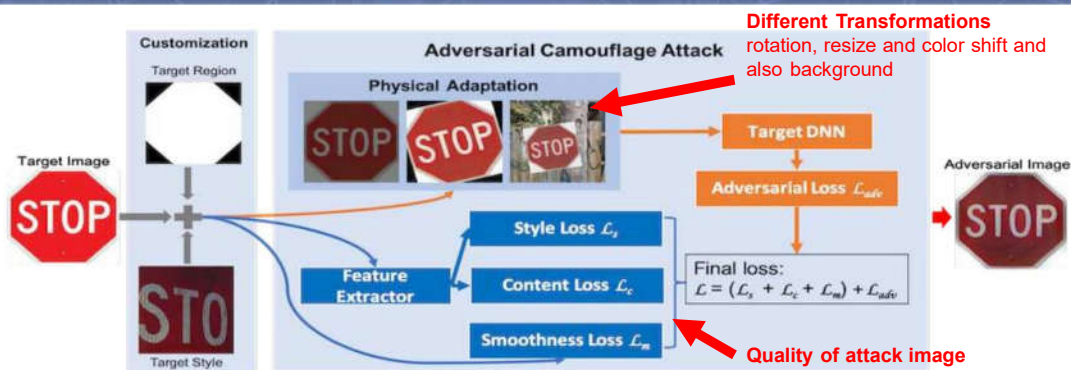
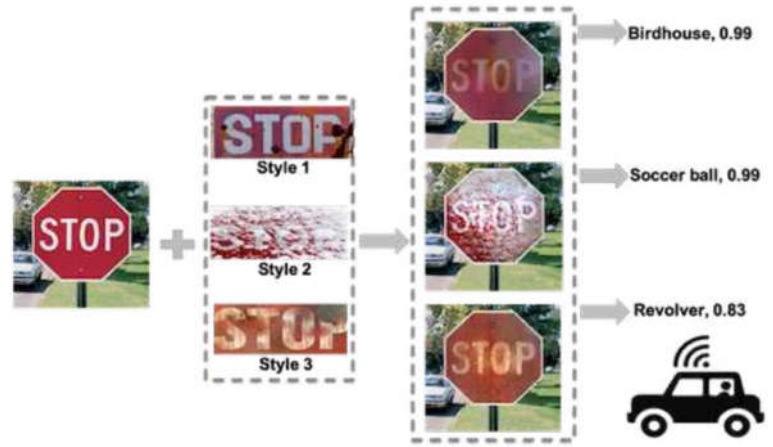
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• Adversarial Camouflage (AdvCam)

- Mislead models by transferring style to objects
 - Use style as adversarial noise
 - Natural styles that appear legitimate to human observers

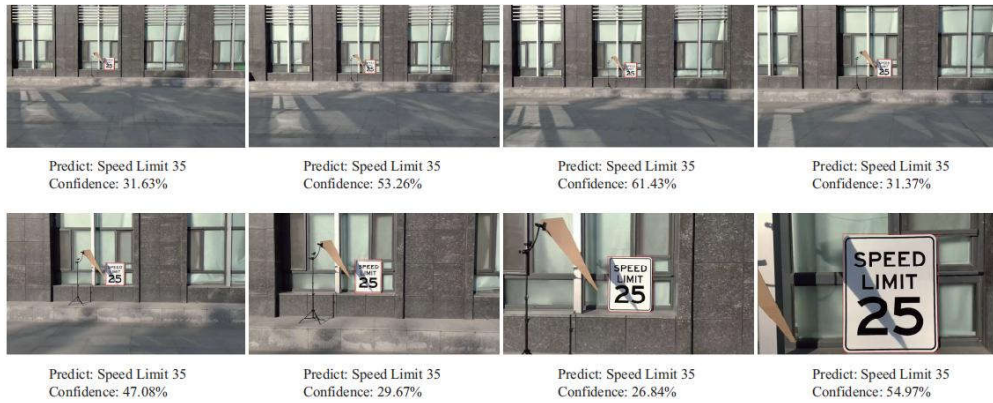




- A shadow with the simplest polygon — triangles, are sufficient to produce successful adversarial examples

$$\arg \min_{\mathcal{V}} f_{true}(S(x, P_{\mathcal{V}}, M, k)), \text{ s.t. } \tilde{y}_{adv} \neq y_{true}$$

$f_{true}()$: confident score of a class
 S : surrogate model
 x : clean picture
 $P_{\mathcal{V}}$: polygon vertices
 M : mask
 k : change pixel values of shadow area



Non-Security Applications





- Hard Sample Generation
- Uncertain Samples Selection

Non-Security Application: Hard Sample Generation Metric Learning

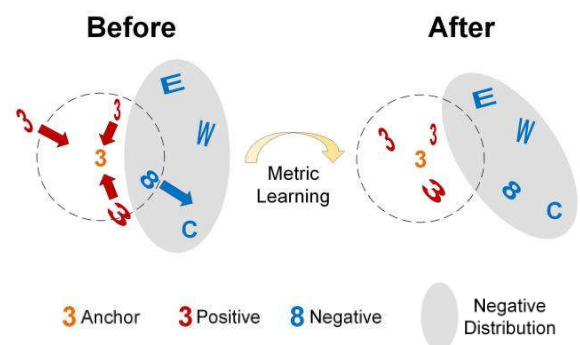


- Aim to generate a **high dimensional space**
 - Similar samples are **close**
 - Different samples are **far away**
- **Triplet Loss** is a general objective function

$$[D(\mathbf{x}_i^+, \mathbf{x}_i)^2 - D(\tilde{\mathbf{x}}_i^-, \mathbf{x}_i)^2 + \alpha]_+$$

Inner Distance Intra Distance

- x : anchor sample
- x^+ : sample of the same class as anchor
- x^- : sample of different class to anchor
- D : distance measure in metric learning space



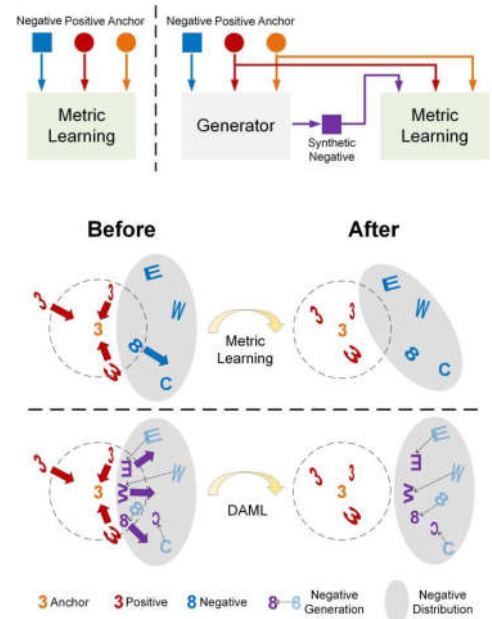
- Problem: **Negative sample** (even chosen by hard sampling) **may not be difficult enough**

Non-Security Application: Hard Sample Generation Metric Learning



- **Craft hard negative samples** by adversarial attack
 - Similar to anchor and original negative sample (J_{hard} & J_{reg})
 - **Generate the negative samples** on which the learned metric would **misclassify** (J_{adv})

$$\begin{aligned} \min_{\theta_g} J_{\text{gen}} &= J_{\text{hard}} + \lambda_1 J_{\text{reg}} + \lambda_2 J_{\text{adv}} \\ &= \sum_{i=1}^N (\|\tilde{\mathbf{x}}_i^- - \mathbf{x}_i\|_2^2 + \lambda_1 \|\tilde{\mathbf{x}}_i^- - \mathbf{x}_i^-\|_2^2 \\ &\quad + \lambda_2 [D(\tilde{\mathbf{x}}_i^-, \mathbf{x}_i)^2 - D(\mathbf{x}_i^+, \mathbf{x}_i)^2 - \alpha]_+) \end{aligned}$$



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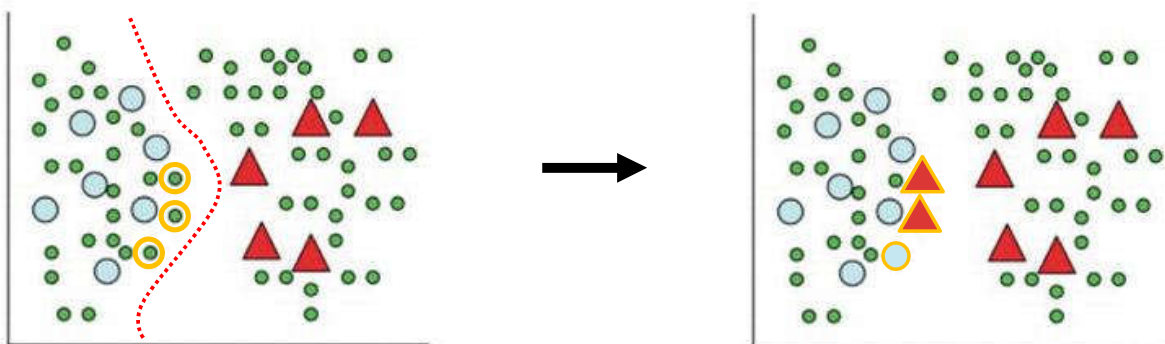
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Y Duan, W Zheng, X Lin(2018) Deep Adversarial Metric Learning . In: CVPR

Non-Security Application: Uncertain Samples Selection Active Learning



- **Select samples for annotation** in semi-supervised learning problem iteratively **based on current model knowledge**
- **Most uncertain samples** are queried



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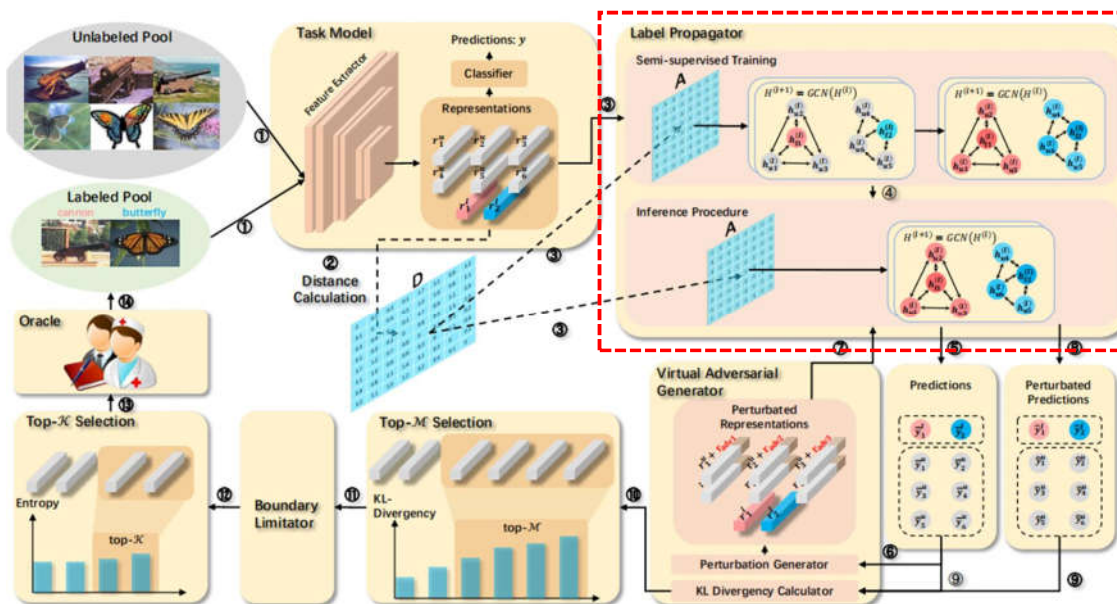
44

Guo J, Shi H, Kang Y(2023) Semi-Supervised Active Learning for Semi-Supervised Models: Exploit Adversarial Examples With Graph-Based Virtual Labels. In: ICCV



• Sample Selection Criterion: **Attack Influence**

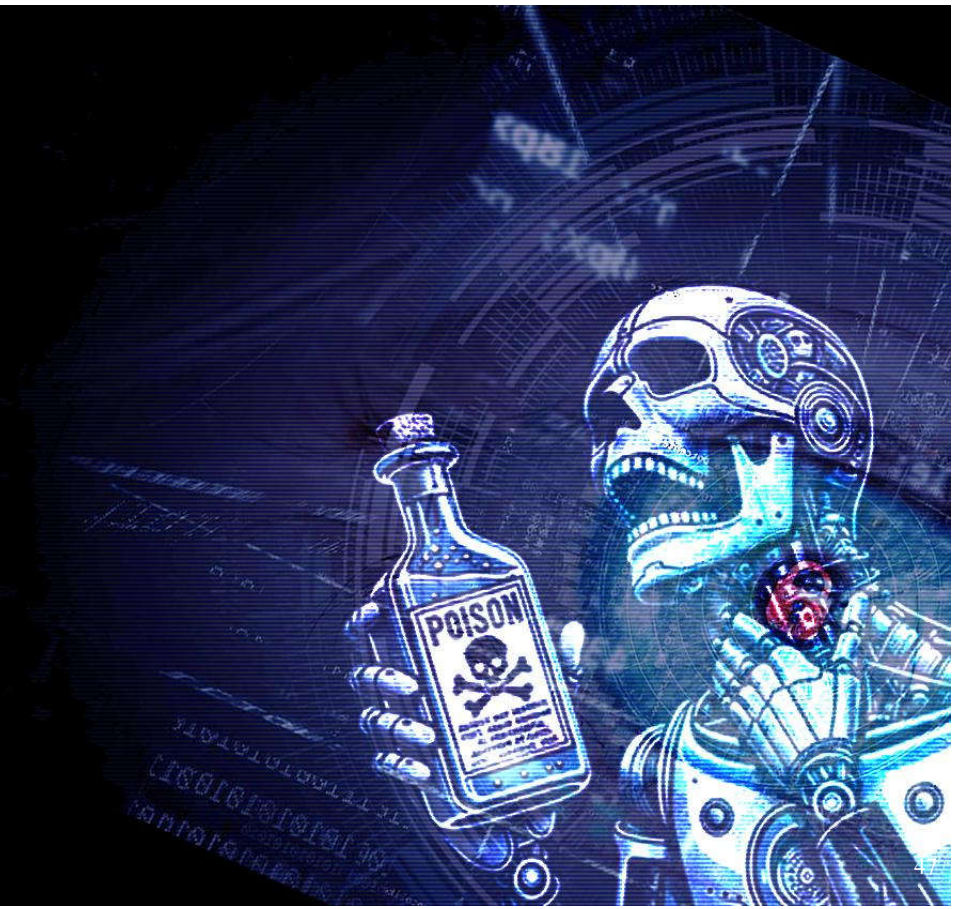
- Labels are propagated to unlabeled samples based on graph convolutional network
- Top-M unlabeled samples are **selected** based on **KL-divergency of outputs of original and its attack sample**
- Top-K out of M are selected by entropy of class outputs for human annotation



Graph Convolutional Network

KL divergency of a sample and its attack sample

To Conclude...



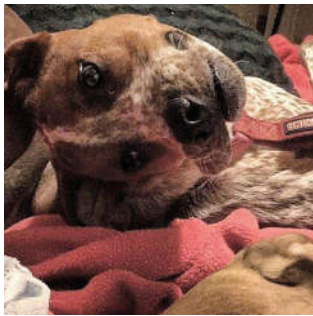
What do you see?



A dog is sitting on a chair?



A monster



What happened to her legs?



A beautiful twin ponytail



The seafront at night



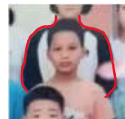
Player with headset



Popcorn



A girl with black sleeves



Damaged Underframe of a vehicle

Don't be Pessimistic



- **Human can also be misled easily and also learn wrongly**
 - Just make **different mistakes from machine learning**
- Adversarial attack significantly harms the security and safety of ML systems, but...
- This threat provides us a chance to **understand better our models and data**

Benefits from Adversarial Attack?



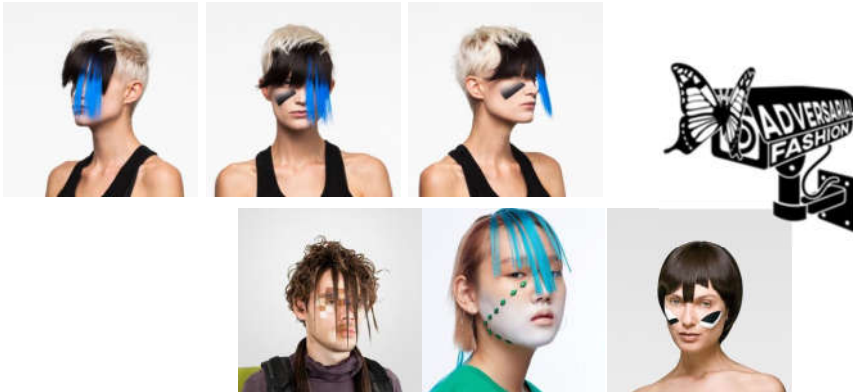
- A coin has two sides?
- Can we benefit from adversarial attack?



Benefits from Adversarial Attack?

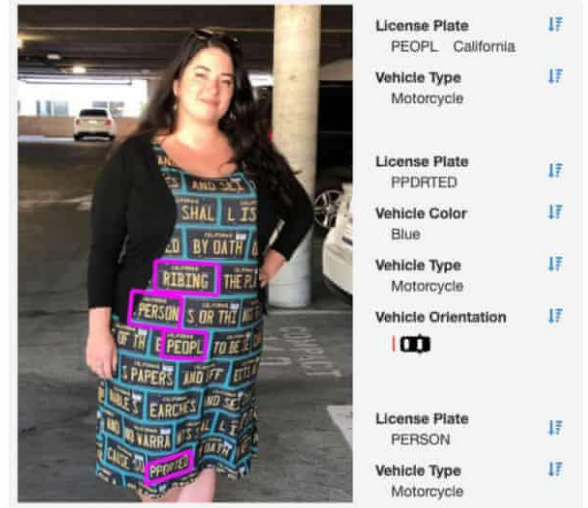


- Avoid surveillance cameras?
- Dress/Fashion/makeup is used to evade or mislead the detection



Key regions: Nose Bridge
nose, eyes, and forehead intersect

<https://cvdazzle.com/>
the-guardian.com/world/2019/aug/13/the-fashion-line-designed-to-trick-surveillance-cameras
<https://adversarialfashion.com/>

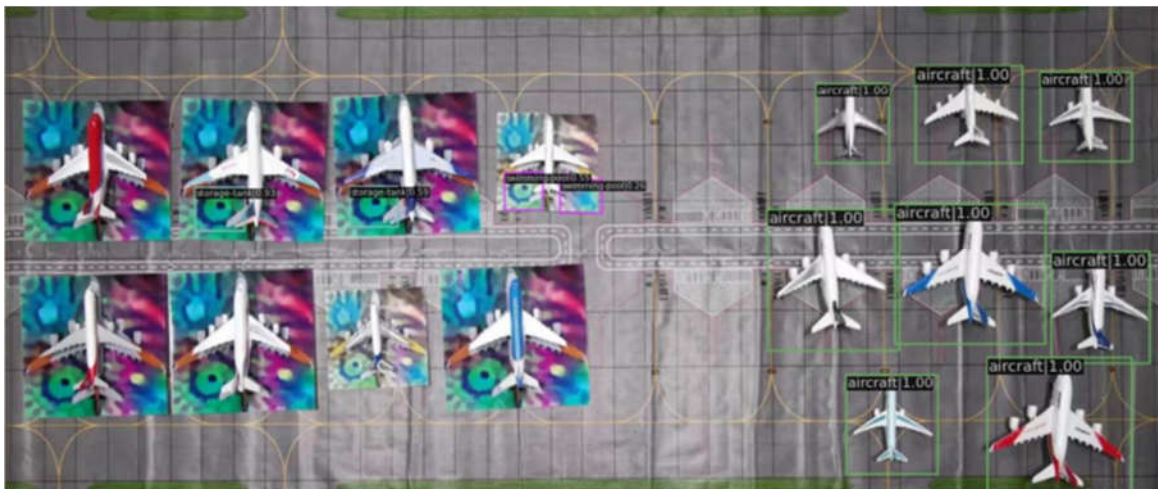


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Benefits from Adversarial Attack?



- Hide from your enemy
- Evade optical aerial detection



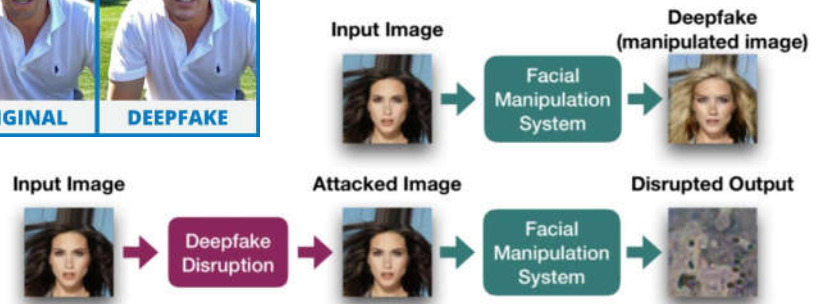
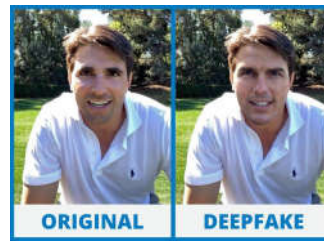
CBA: Contextual Background Attack against Optical Aerial Detection in the Physical World In:arXiv

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Benefits from Adversarial Attack?



- Modified images of a person can be generated **without consent**, e.g. Deepfake
- Disrupt resulting images by adding adversarial noise to a photo



Nataniel Ruiz, Sarah Adel Bargal, Stan Sclaroff(2020) Disrupting Deepfakes: Adversarial Attacks Against Conditional Image Translation Networks and Facial Manipulation Systems. In:arXiv

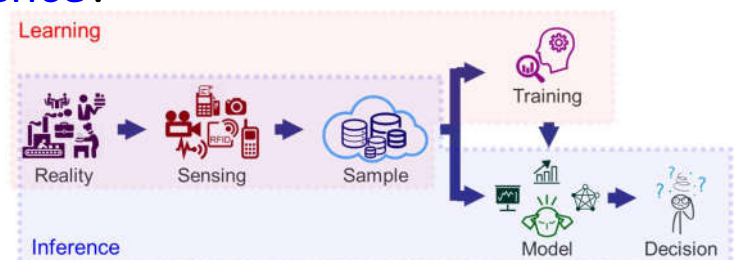
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Key Questions



- Where does **the training data** come from?
 - Provided by a third party?
- Who develops **the model**?
 - Is **pretrained model** used? If yes, where does it from?
- Who knows **the model details**?
- How to **capture samples** in inference?



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• Adversarial Learning Python Library

- Microsoft: Counterfit

<https://github.com/Azure/counterfit/>



- IBM: Adversarial Robustness Toolbox

<https://github.com/Trusted-AI/adversarial-robustness-toolbox>

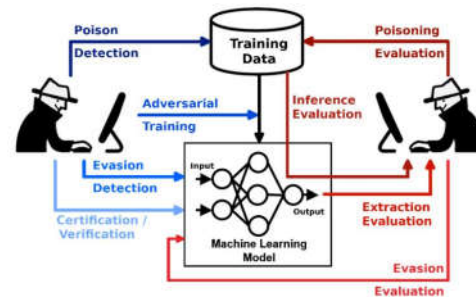


- Pluribus One: SecML (Secure ML Library)

<https://www.pluribus-one.it/research/sec-ml/sec-ml-lib>



- For Research and Engineering purposes



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Welcome to Join Us!



- Besides publications...
- What you will learn...
 - Soft-Skill
 - Critical Thinking
 - Analytical Skill
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